

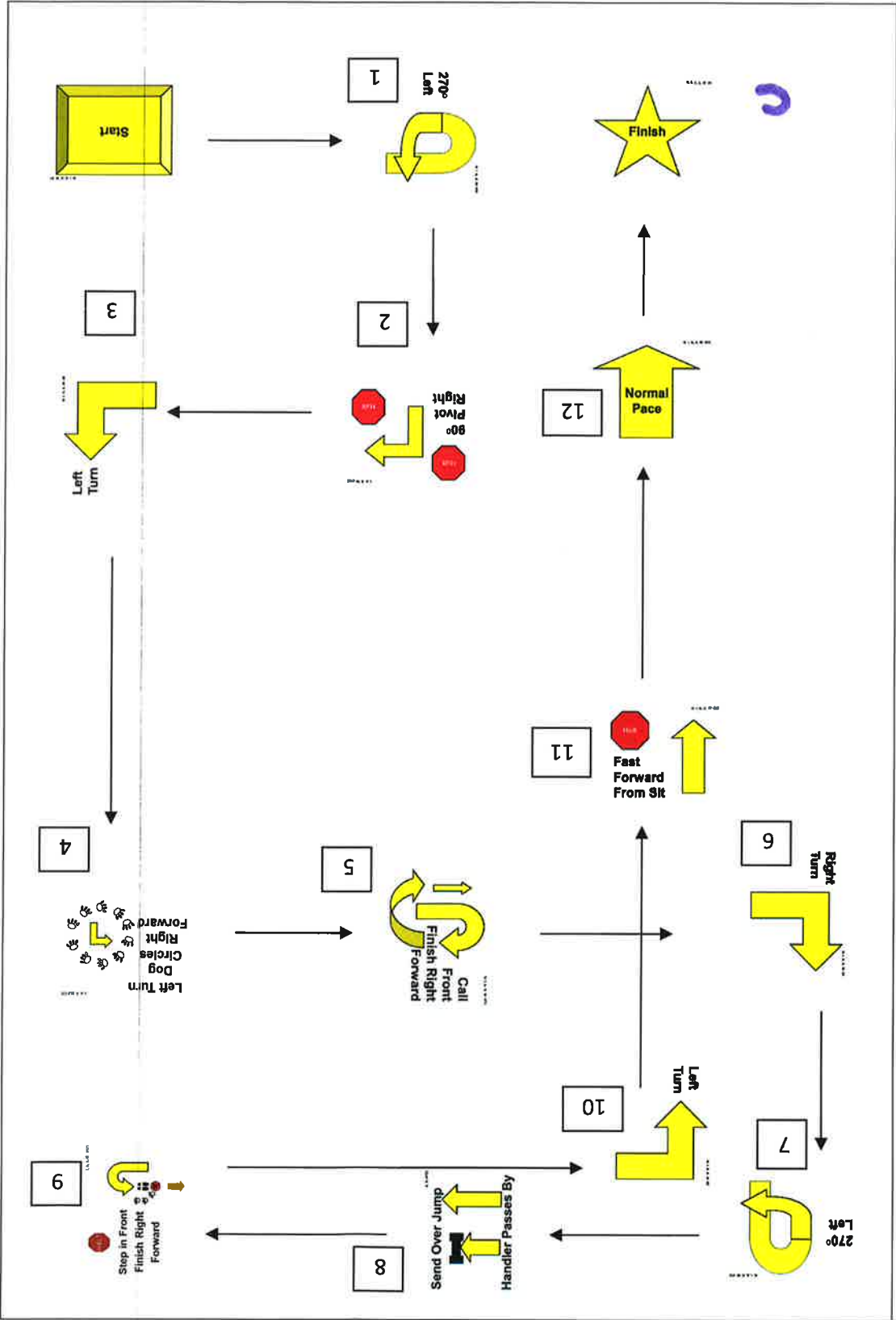
ADVANCED

START (1)

1. 270° Left Turn (10)
2. HALT - 90° Pivot Right (-HALT (106))
3. Left Turn (6)
4. Left Turn - Dog Circles Right - Forward (120)
5. Call Front - Finish Right - Forward (13)
6. Right Turn (5)
7. 270° Left Turn (10)
8. Send over Jump - Handler Passes By
9. HALT - Step in Front - Finish Right - Forward (121)
10. Left Turn (6)
11. HALT - Fast Forward From Sit (28)
12. Normal Pace (19)

FINISH (2)

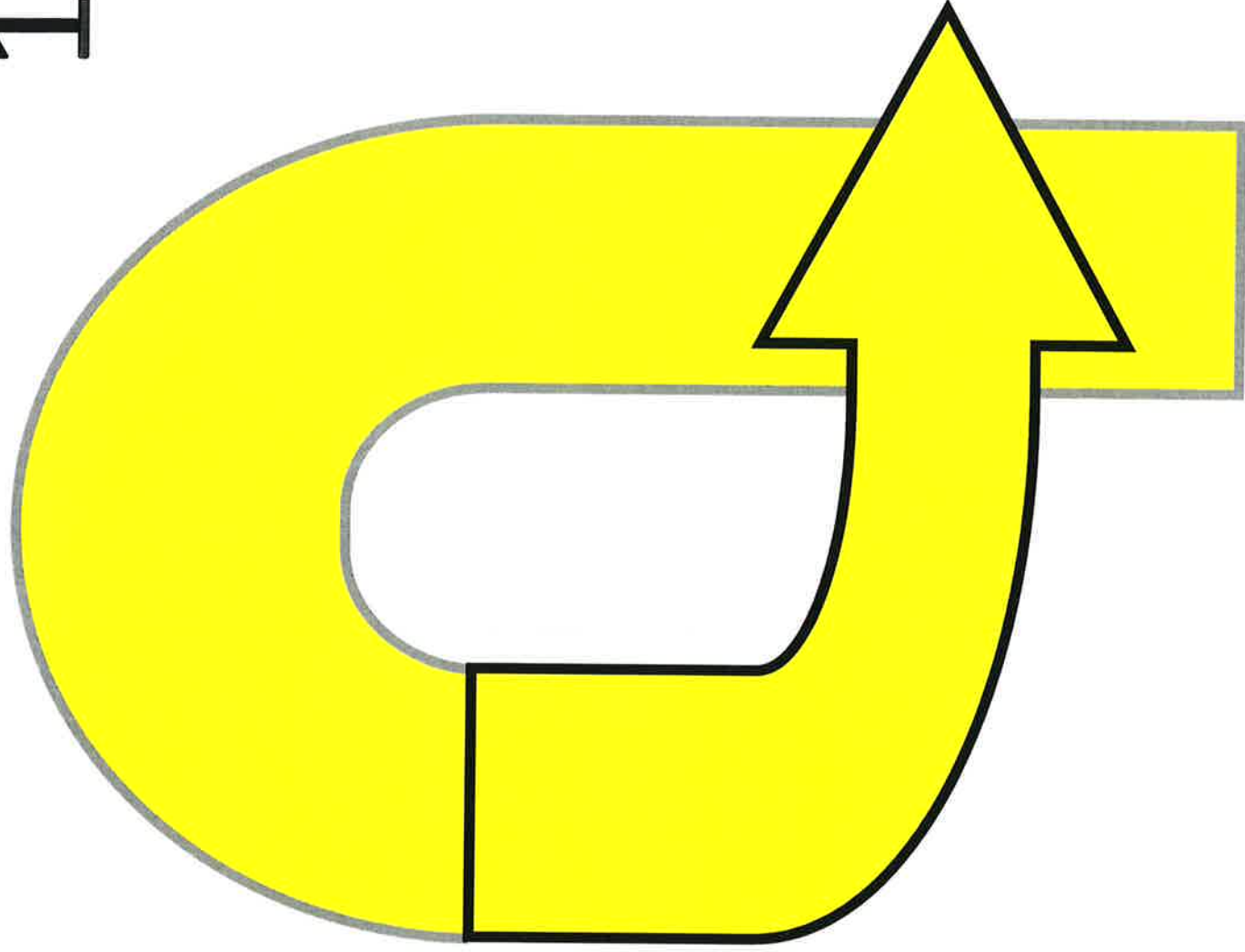
1. 270° Left Turn (10)
2. HALT - 90° Pivot Right (-HALT (106))
3. Left Turn (6)
4. Left Turn - Dog Circles Right - Forward (120)
5. Call Front - Finish Right - Forward (13)
6. Right Turn (5)
7. 270° Left Turn (10)
8. Send over Jump - Handler Passes By
9. HALT - Step in Front - Finish Right - Forward (121)
10. Left Turn (6)
11. HALT - Fast Forward From Sit (28)
12. Normal Pace (19)



N, I, A, X, M- #1

Start

1



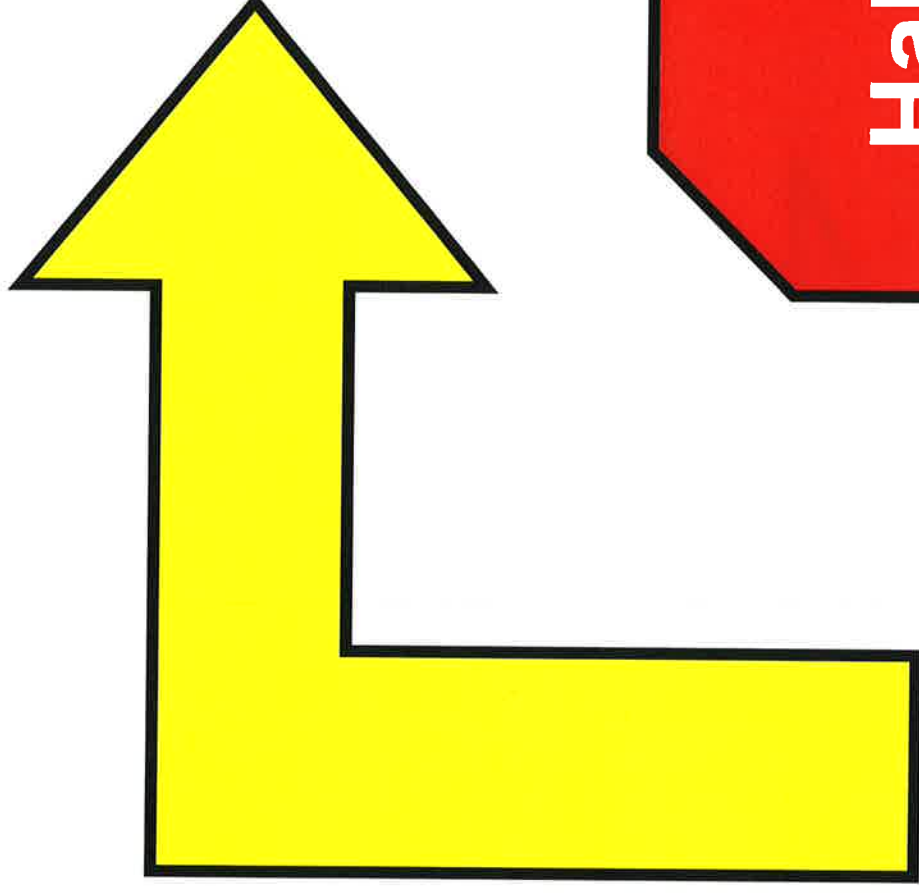
270°

Left

2

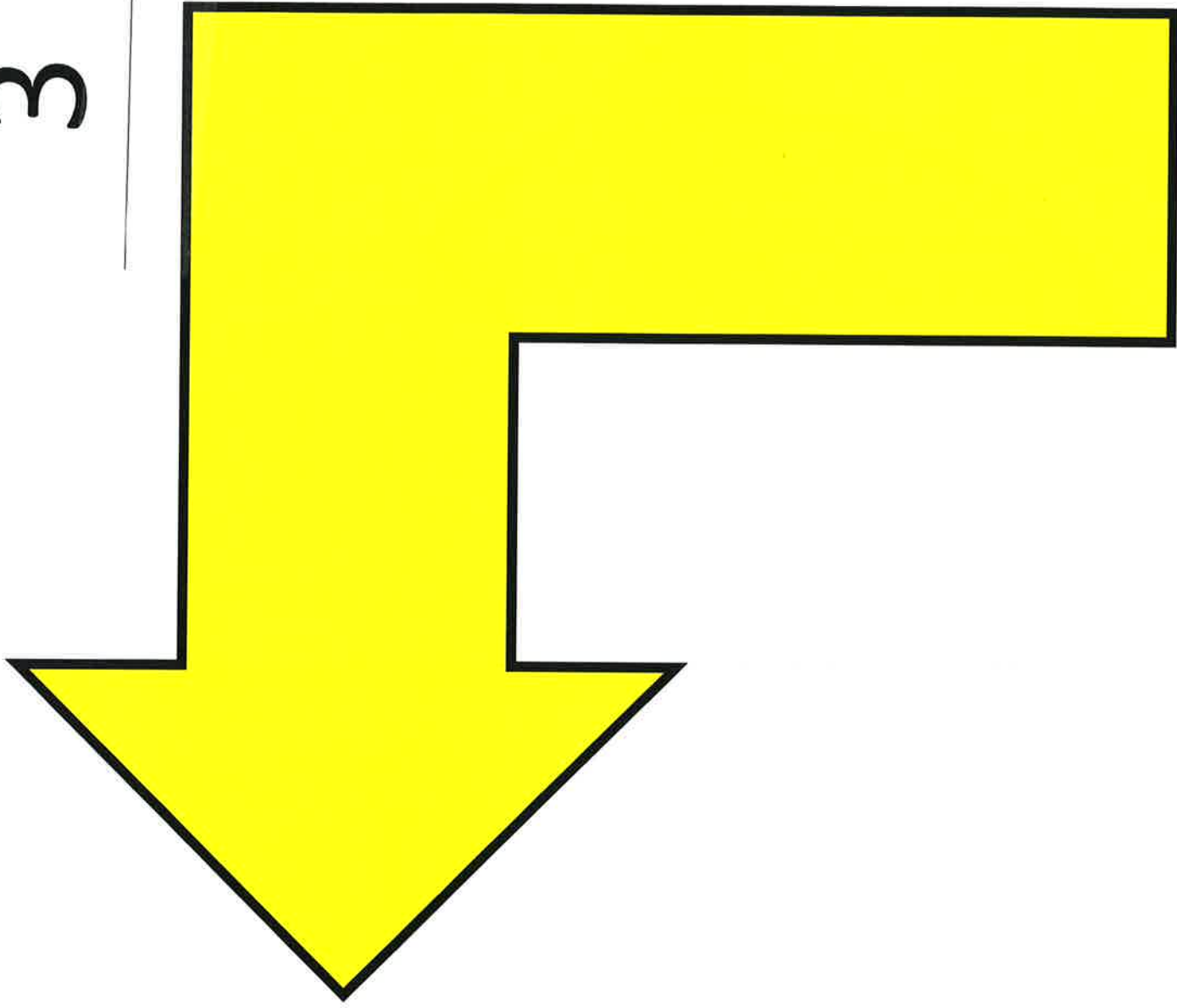


**90°
Pivot
Right**

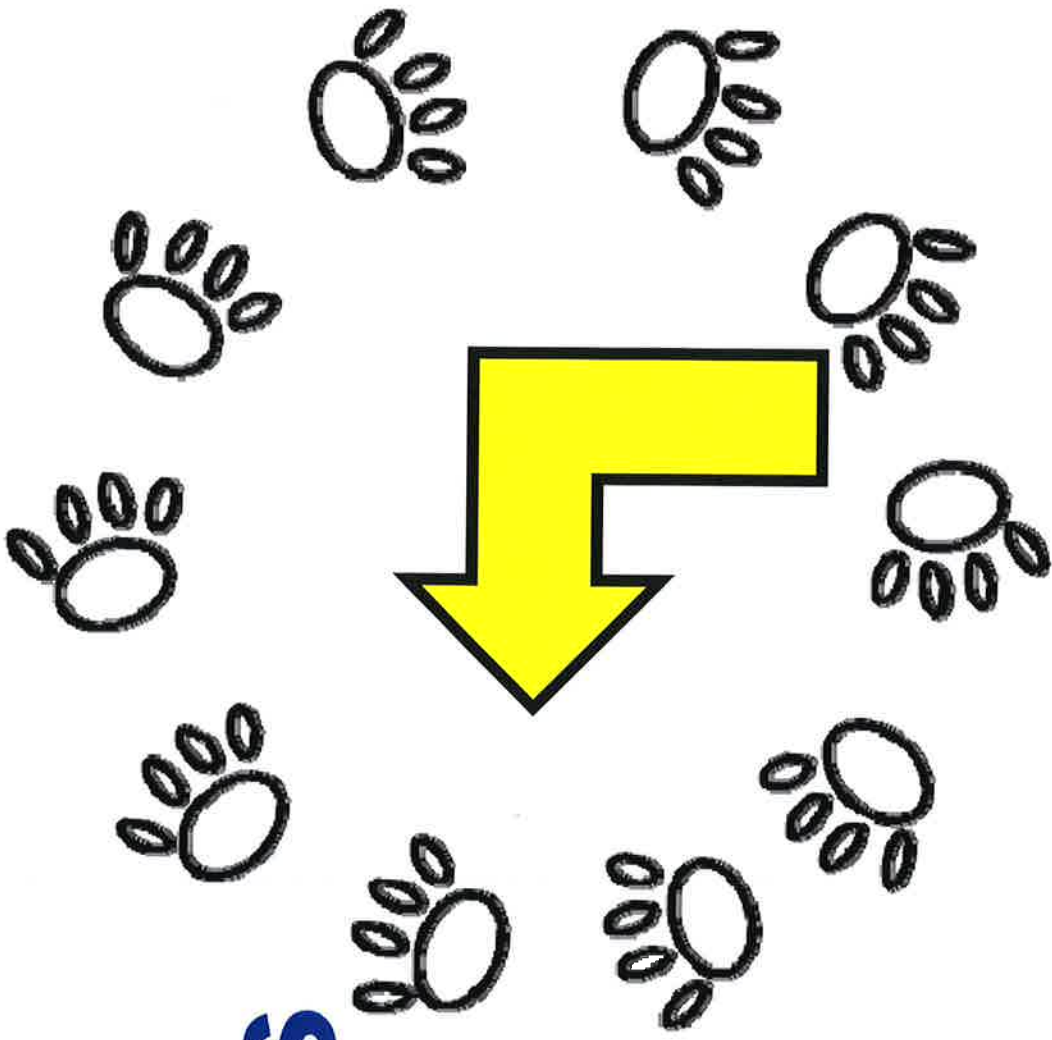


**Left
Turn**

3

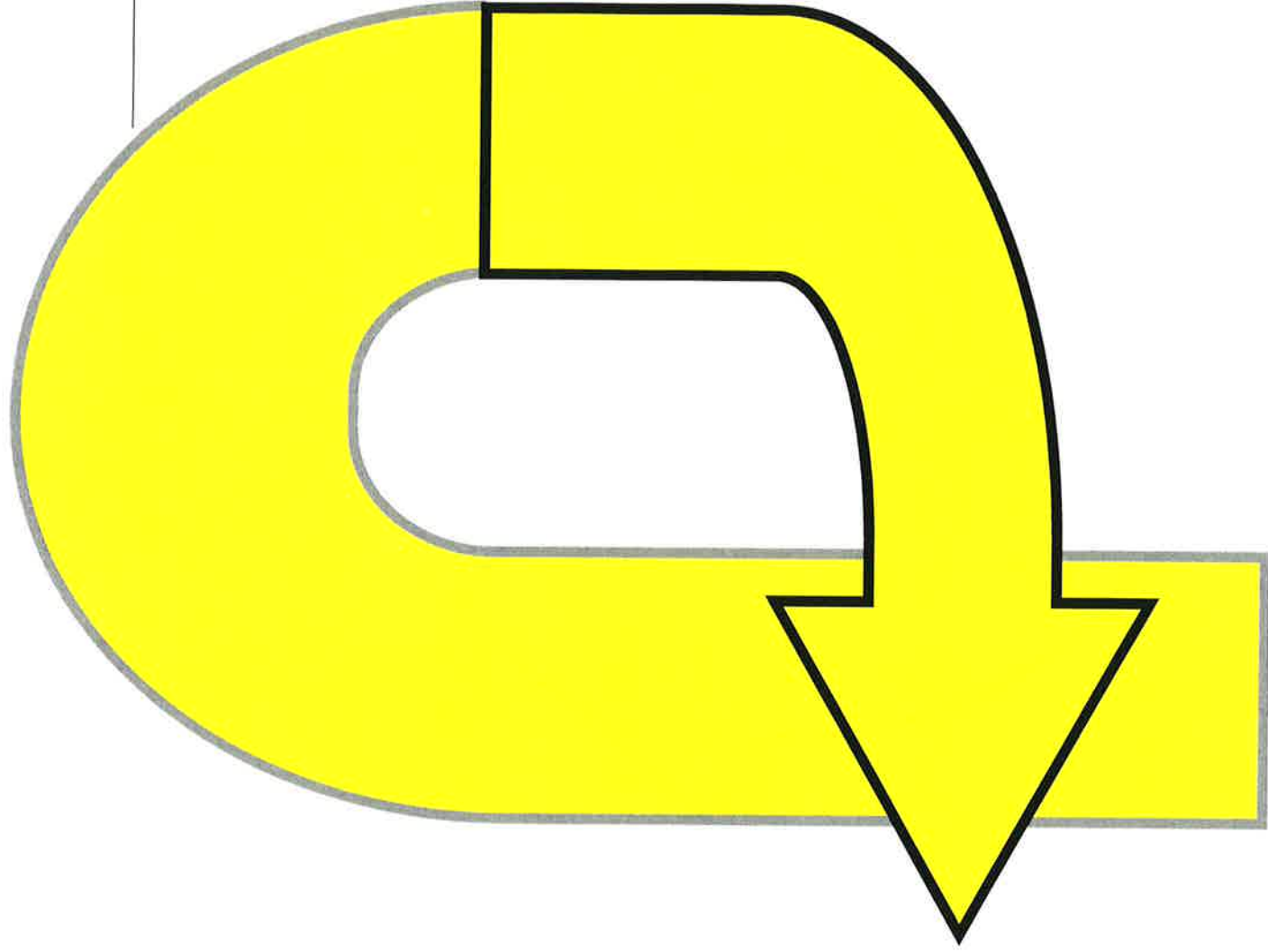


Left Turn
Dog Circles
Right
Forward



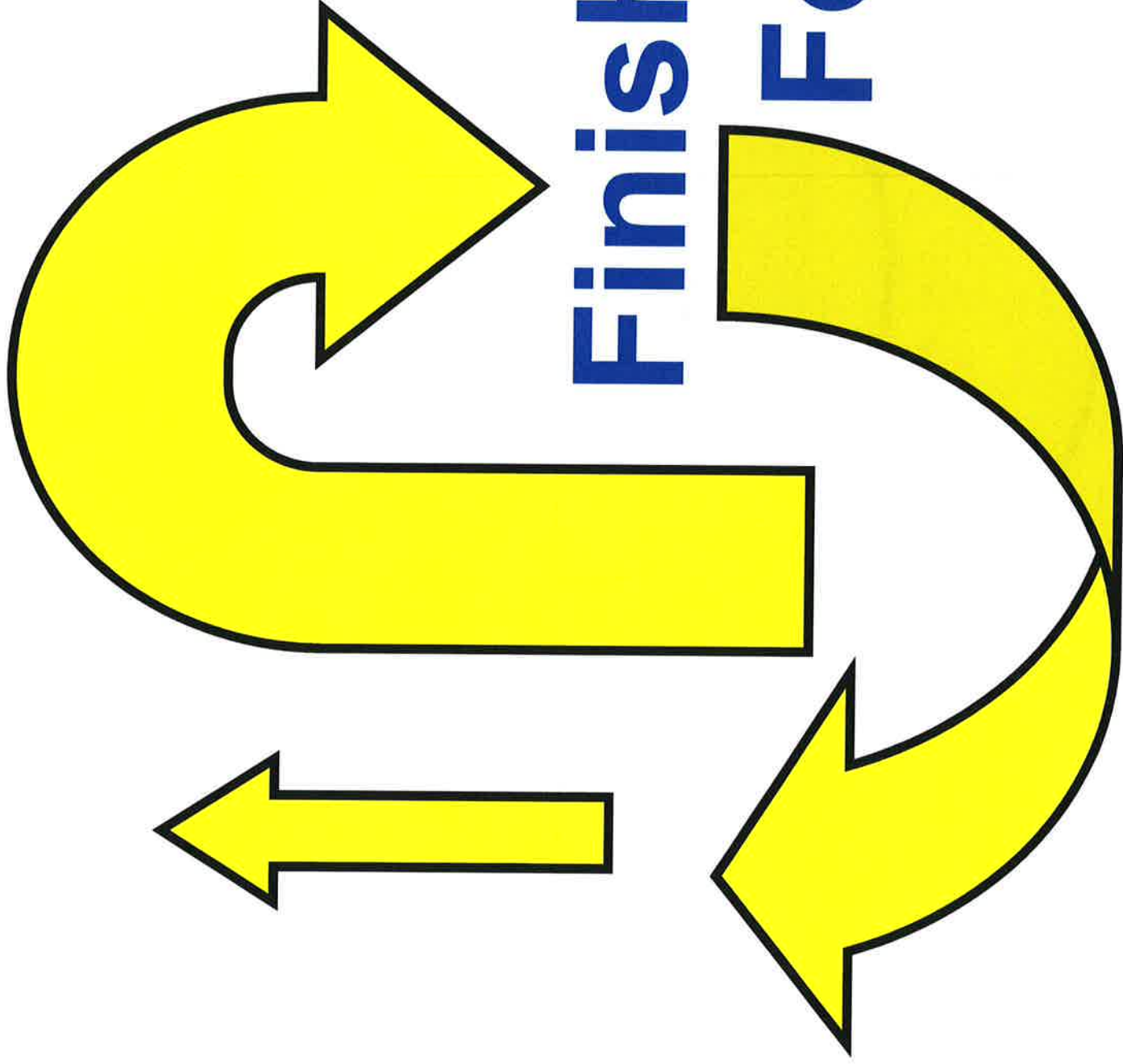
**270°
Right**

4

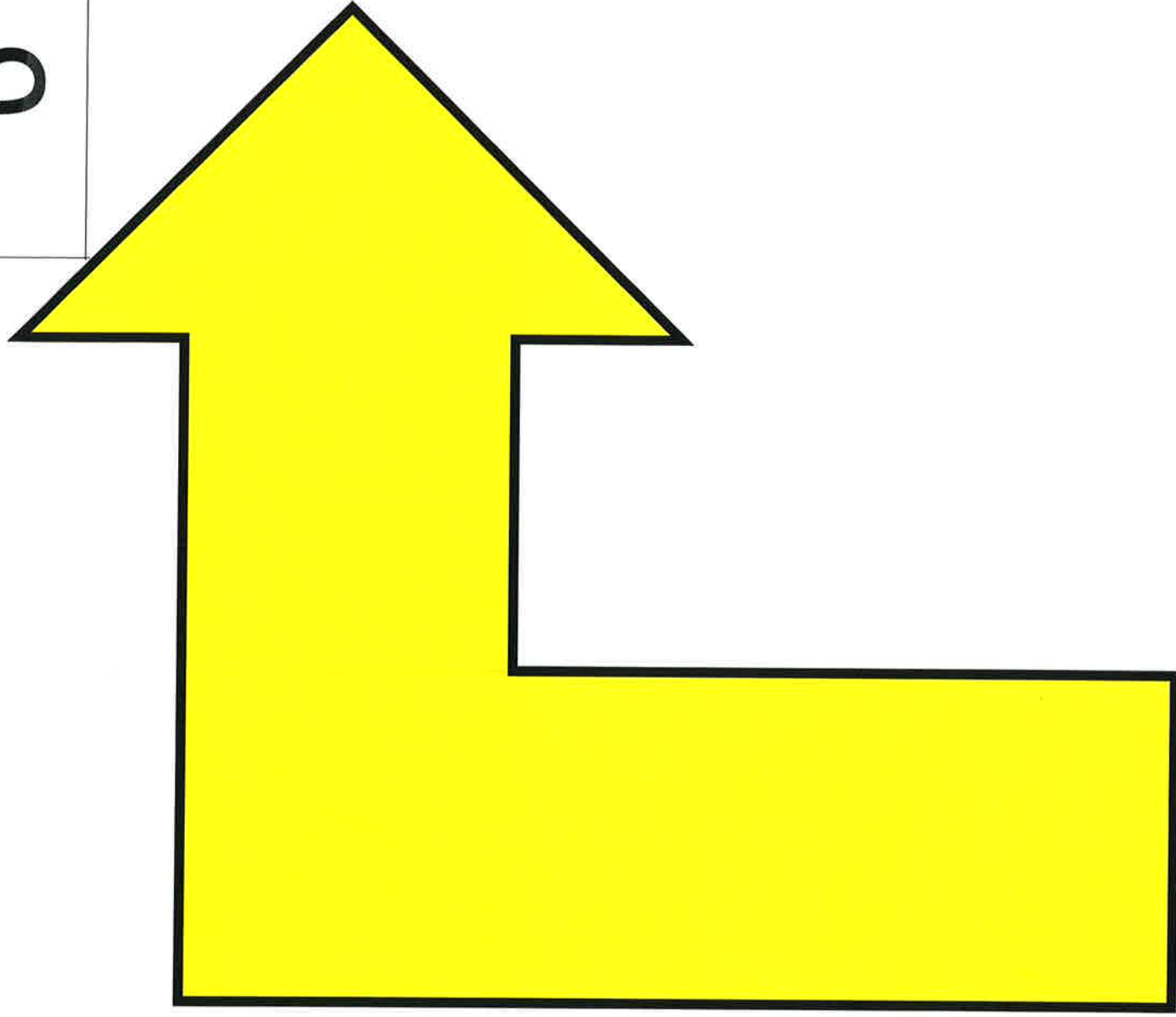


5

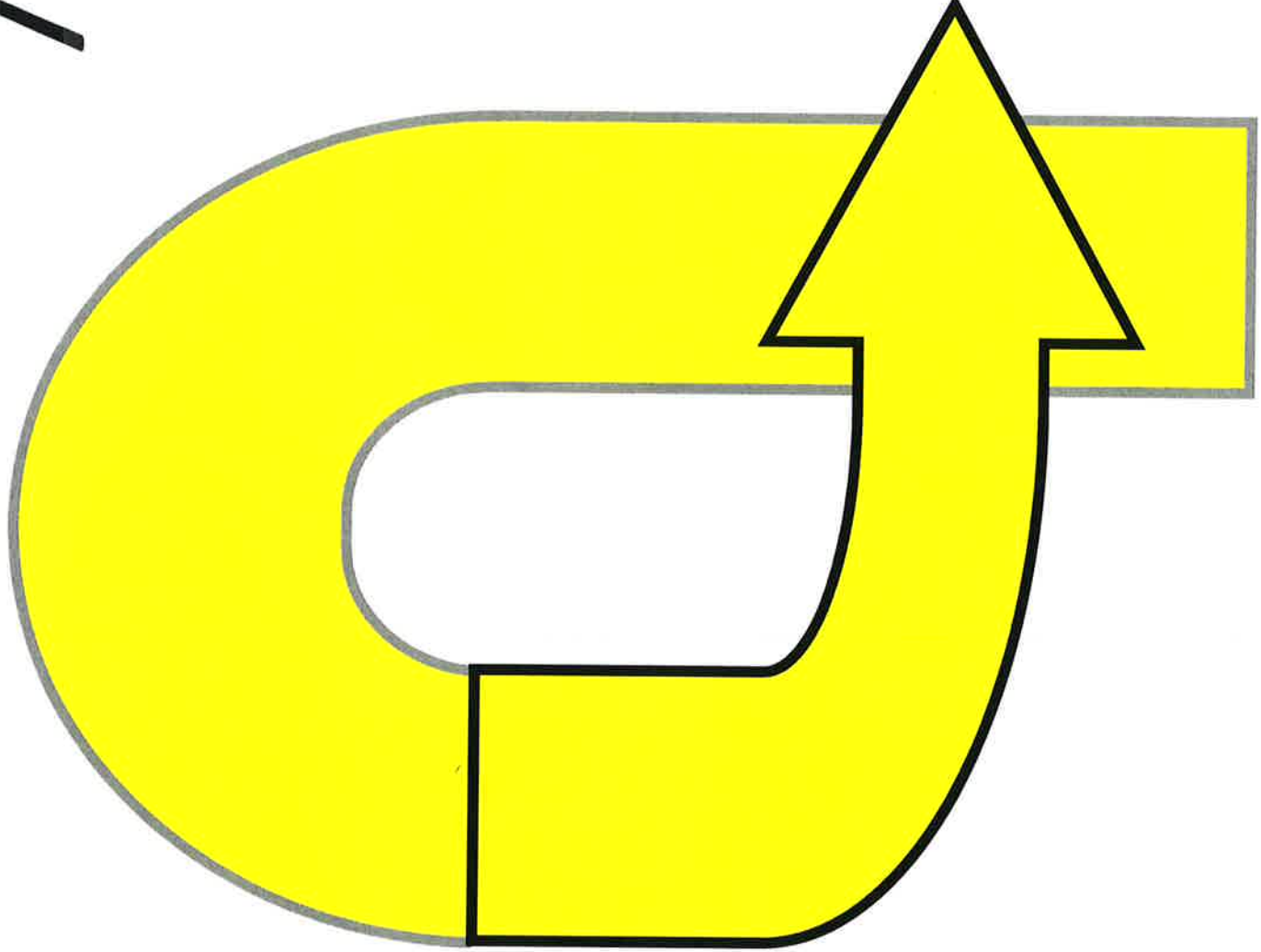
Call
Front
Finish Right
Forward



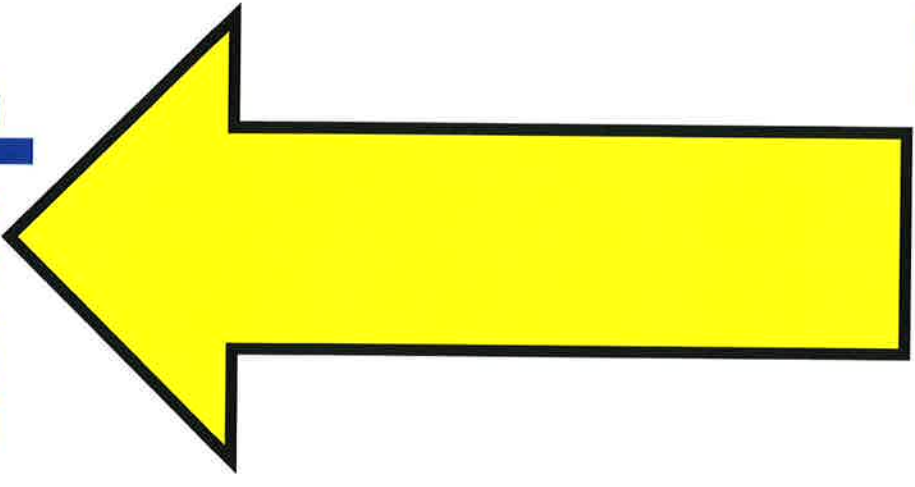
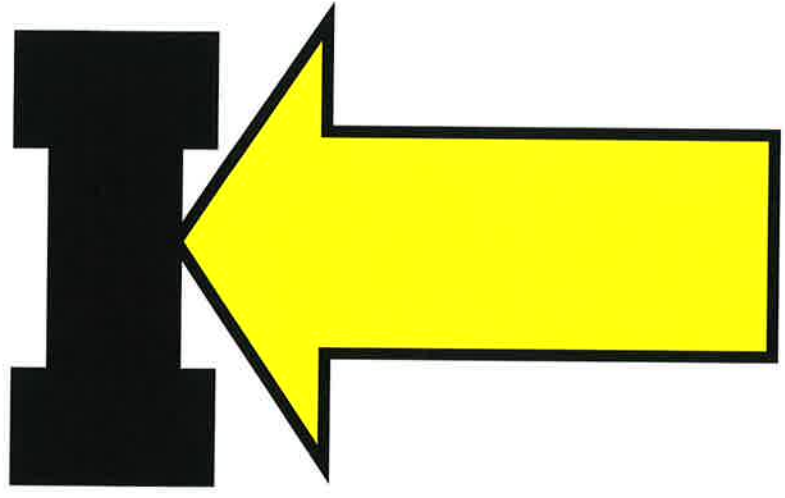
**Right
Turn**



**270°
Left**



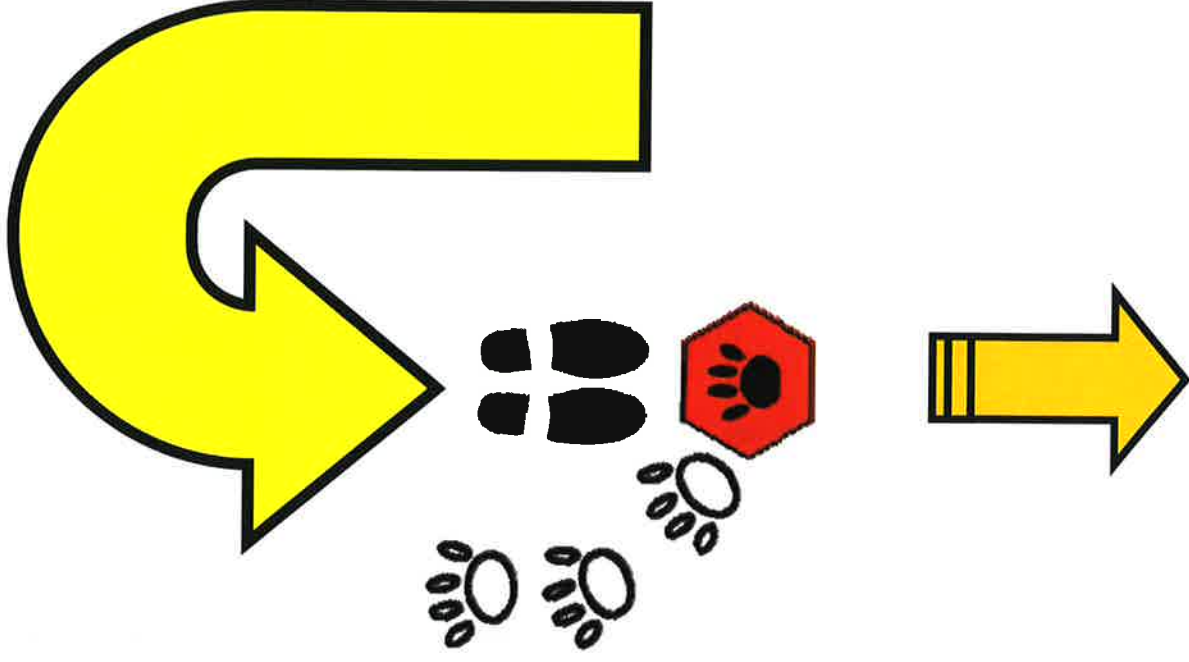
Send Over Jump



Handler Passes By

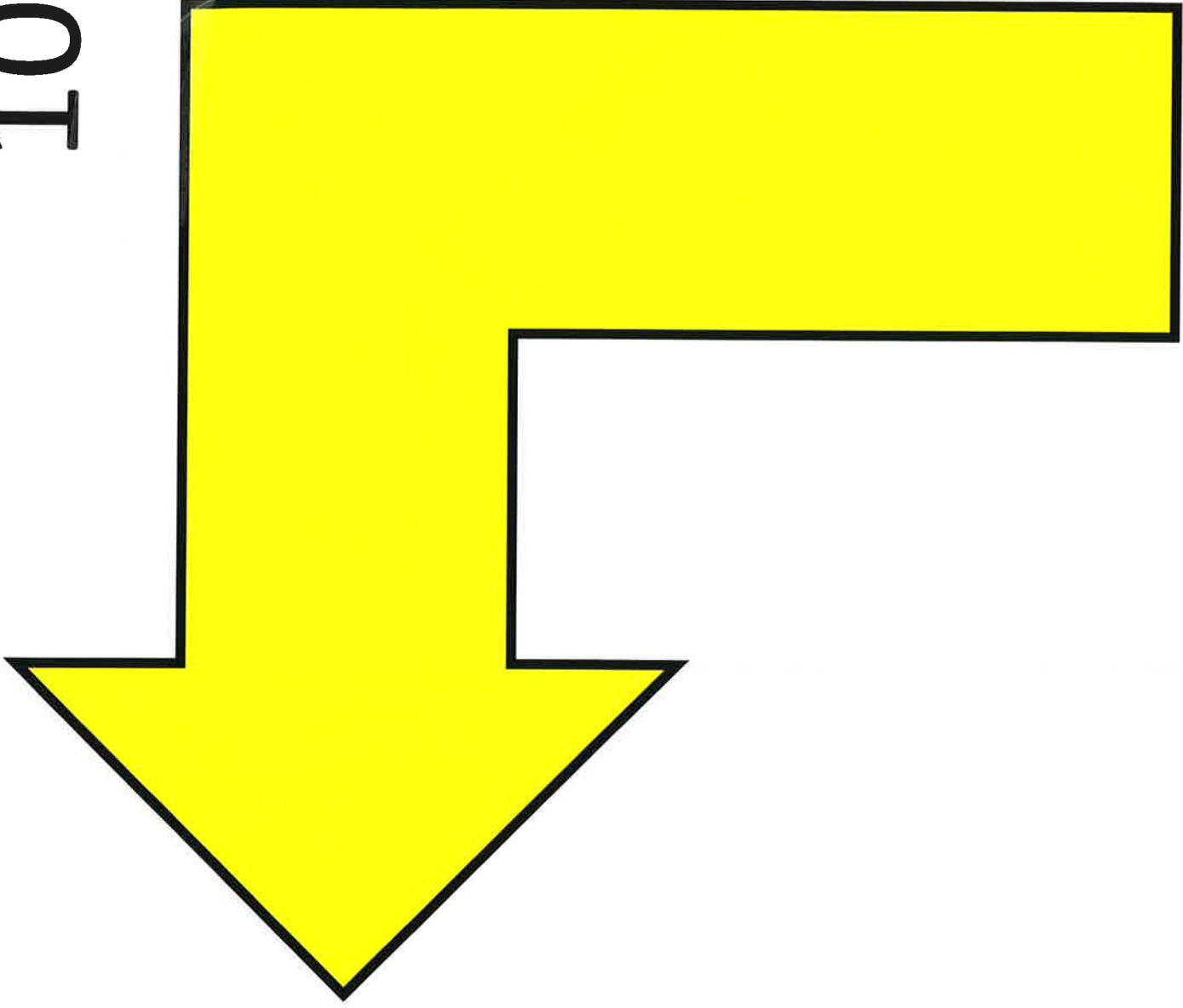


Step in Front
Finish Right
Forward

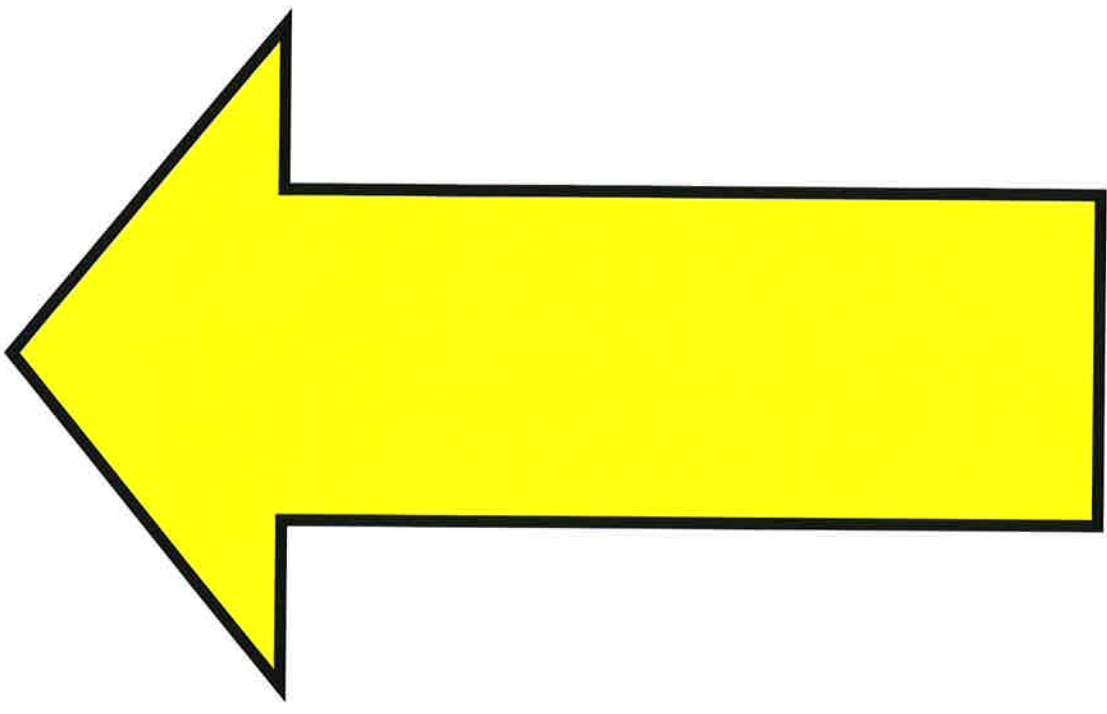


**Left
Turn**

10



11



Fast

Forward

From Sit



**Normal
Pace**

N, I, A, X, M- #2

