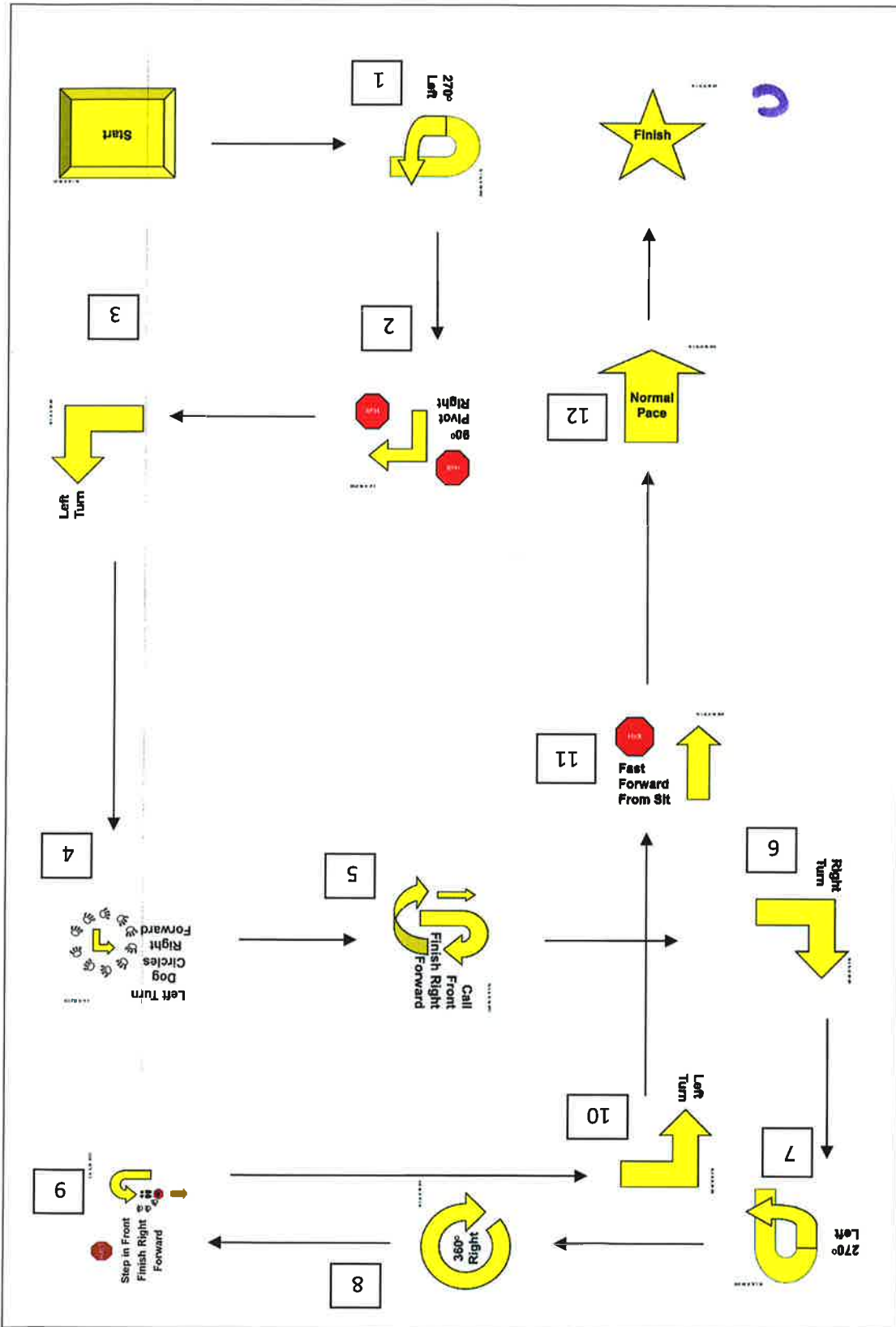


# INTERMEDIATE

## START (1)

1. 270° Left Turn (10)
2. HALT - 90° Pivot Right
3. Left Turn (6)
4. Left Turn - Dog Circles
5. Right - Forward (120)
6. Call Front - Finish
7. Right - Forward (13)
8. Right Turn (5)
9. 270° Left Turn (10)
10. HALT - Step in Front
11. 360° Right Turn (11)
12. HALT - Step in Front
13. Finish Right - Forward
14. Left Turn (6)
15. HALT - Fast Forward
16. Normal Pace (19)
17. FINISH (2)



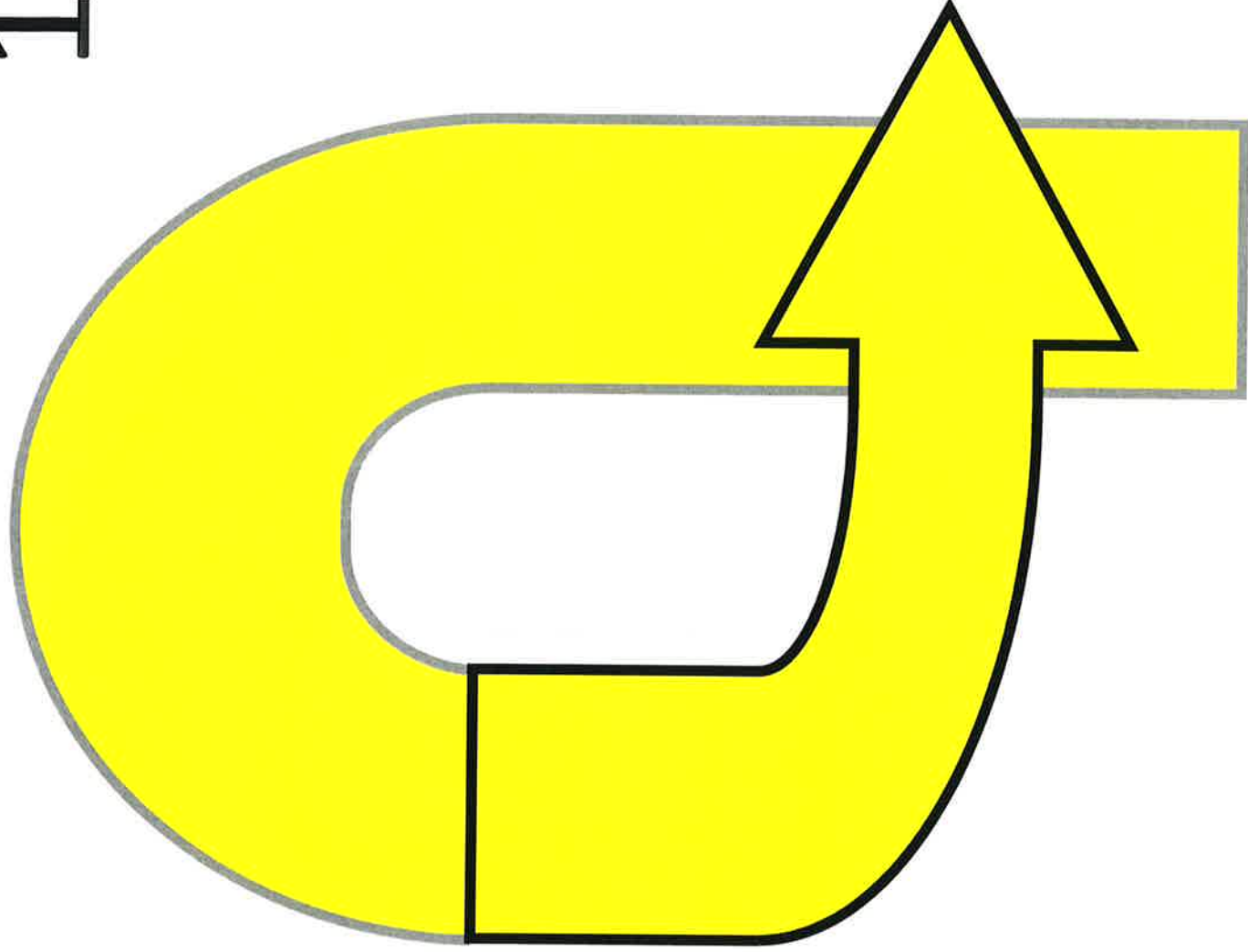
N, I, A, X, M- #1

**Start**

**270°**

**Left**

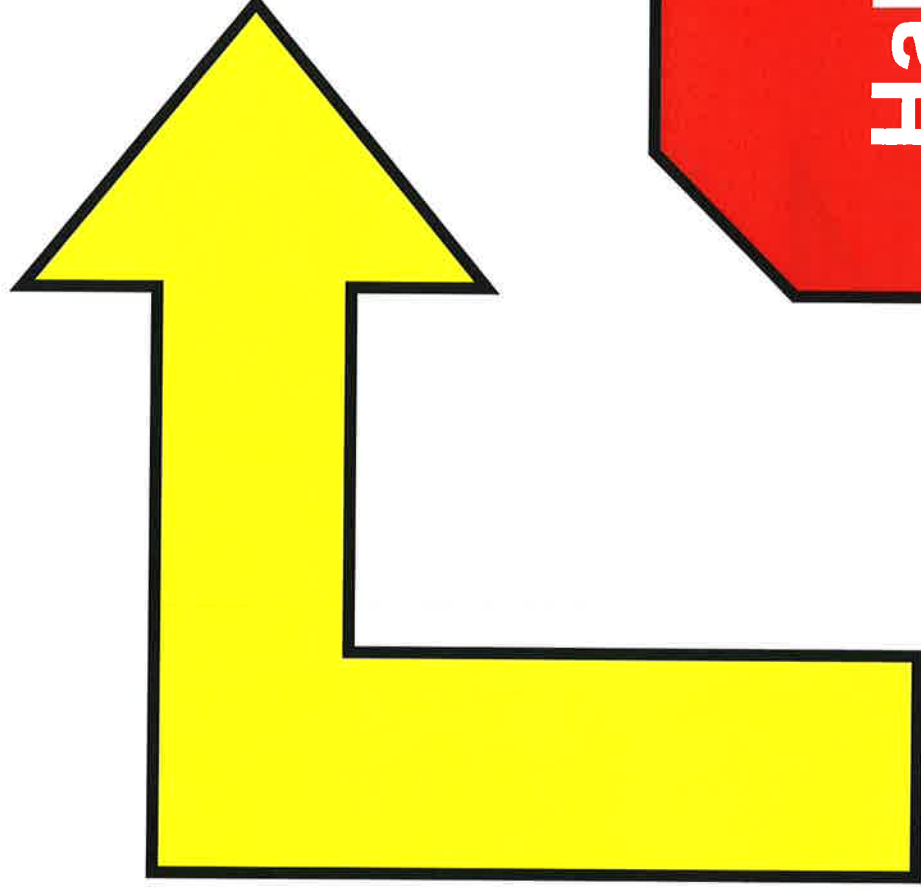
1



2

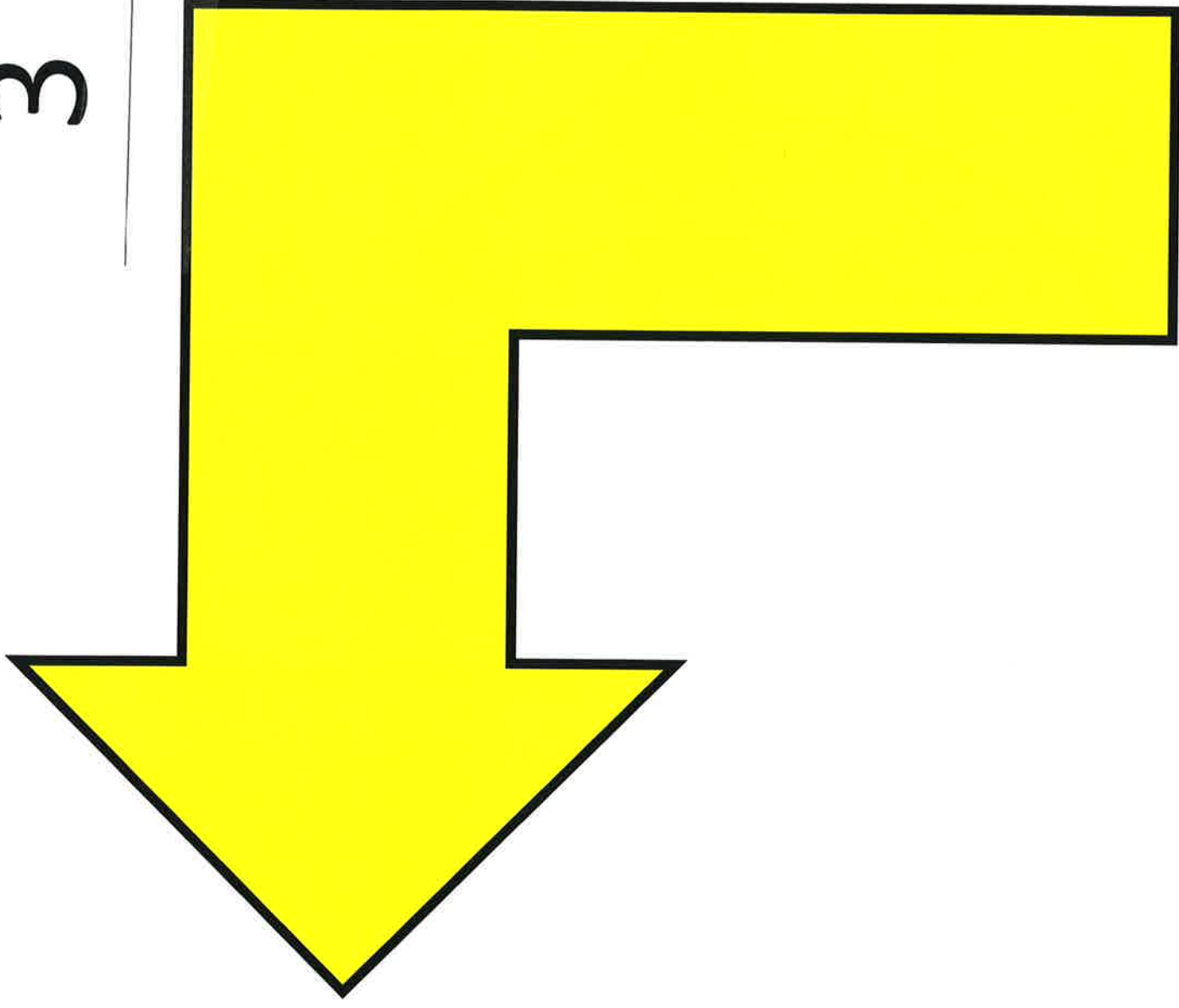


**90°**  
**Pivot**  
**Right**



**Left  
Turn**

3

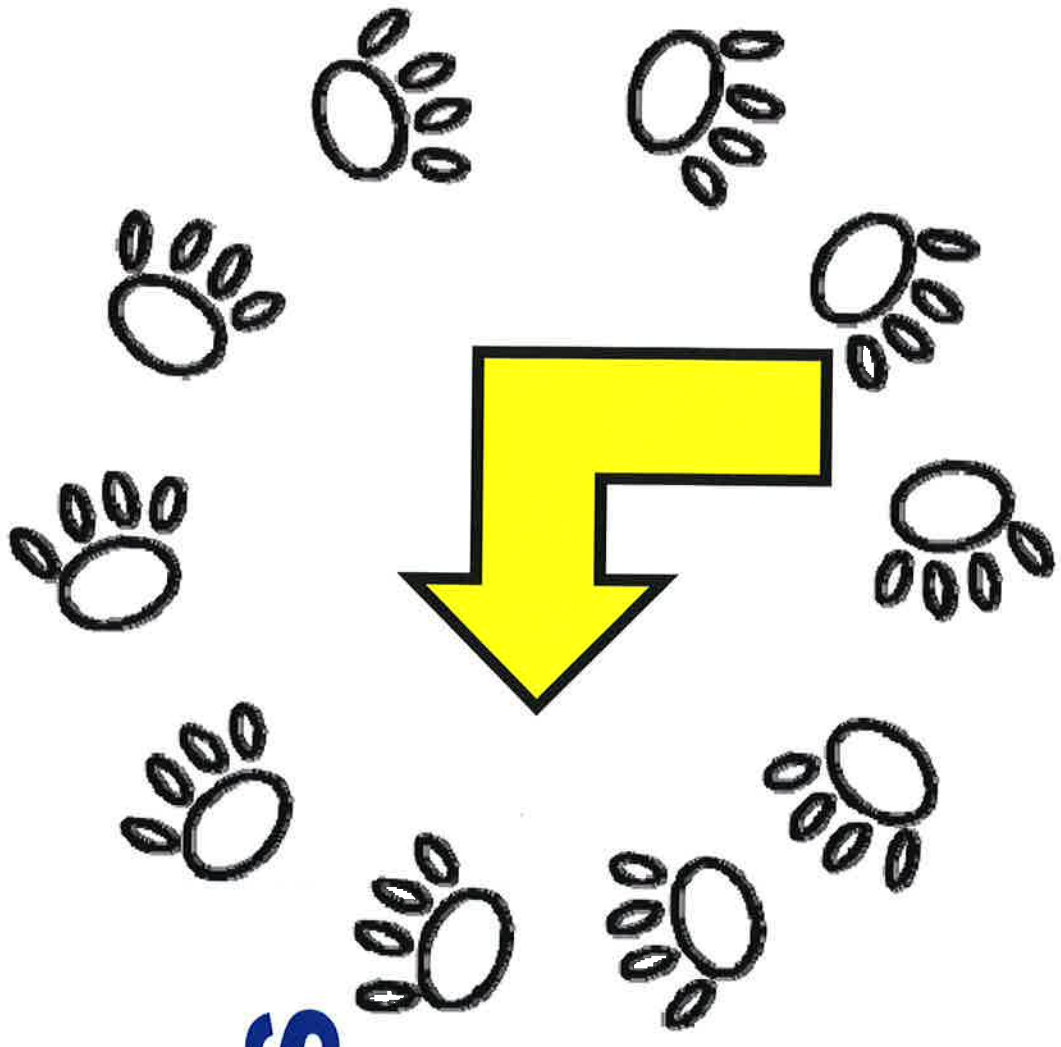


**Left Turn**

**Dog Circles**

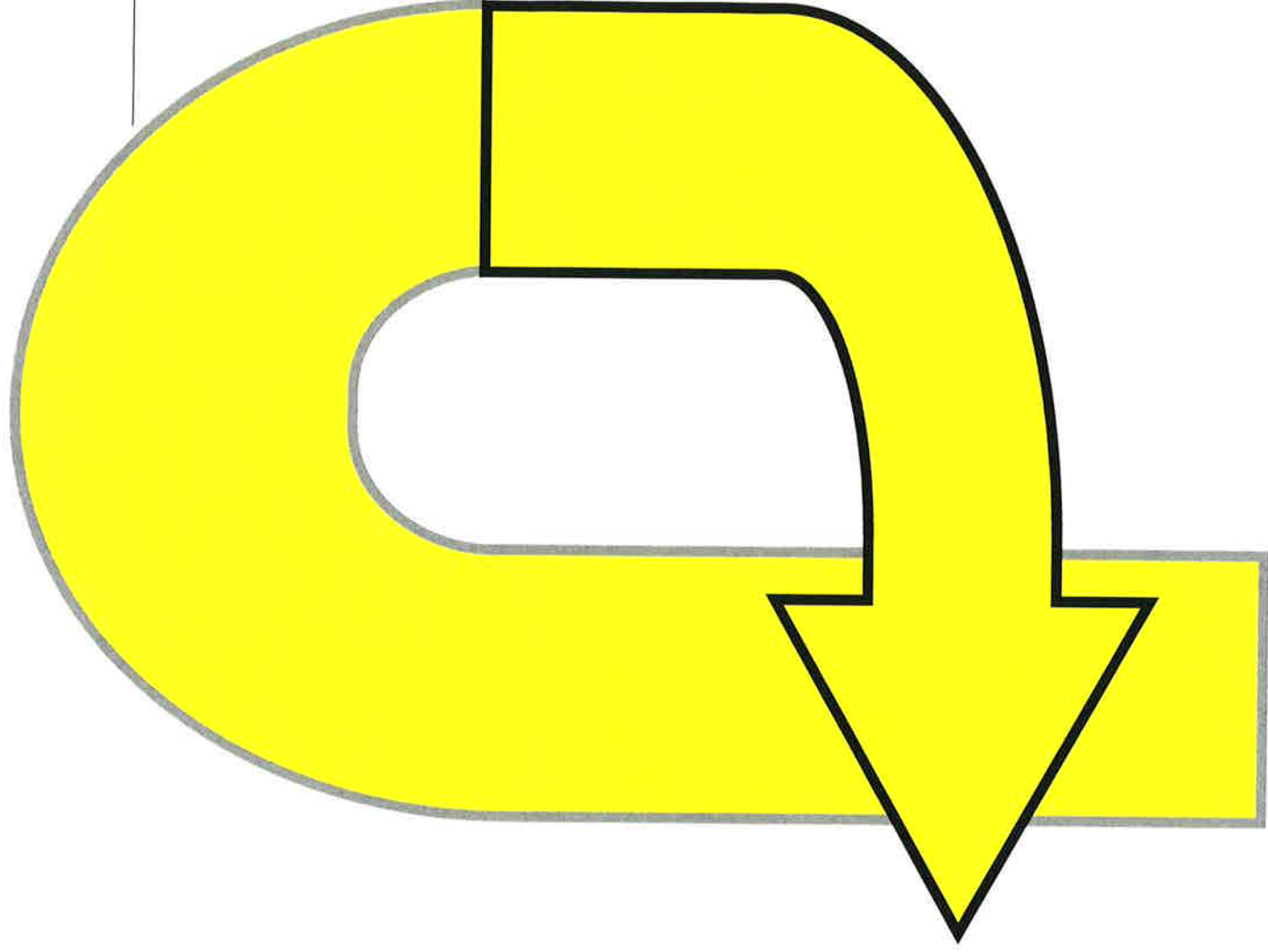
**Right**

**Forward**



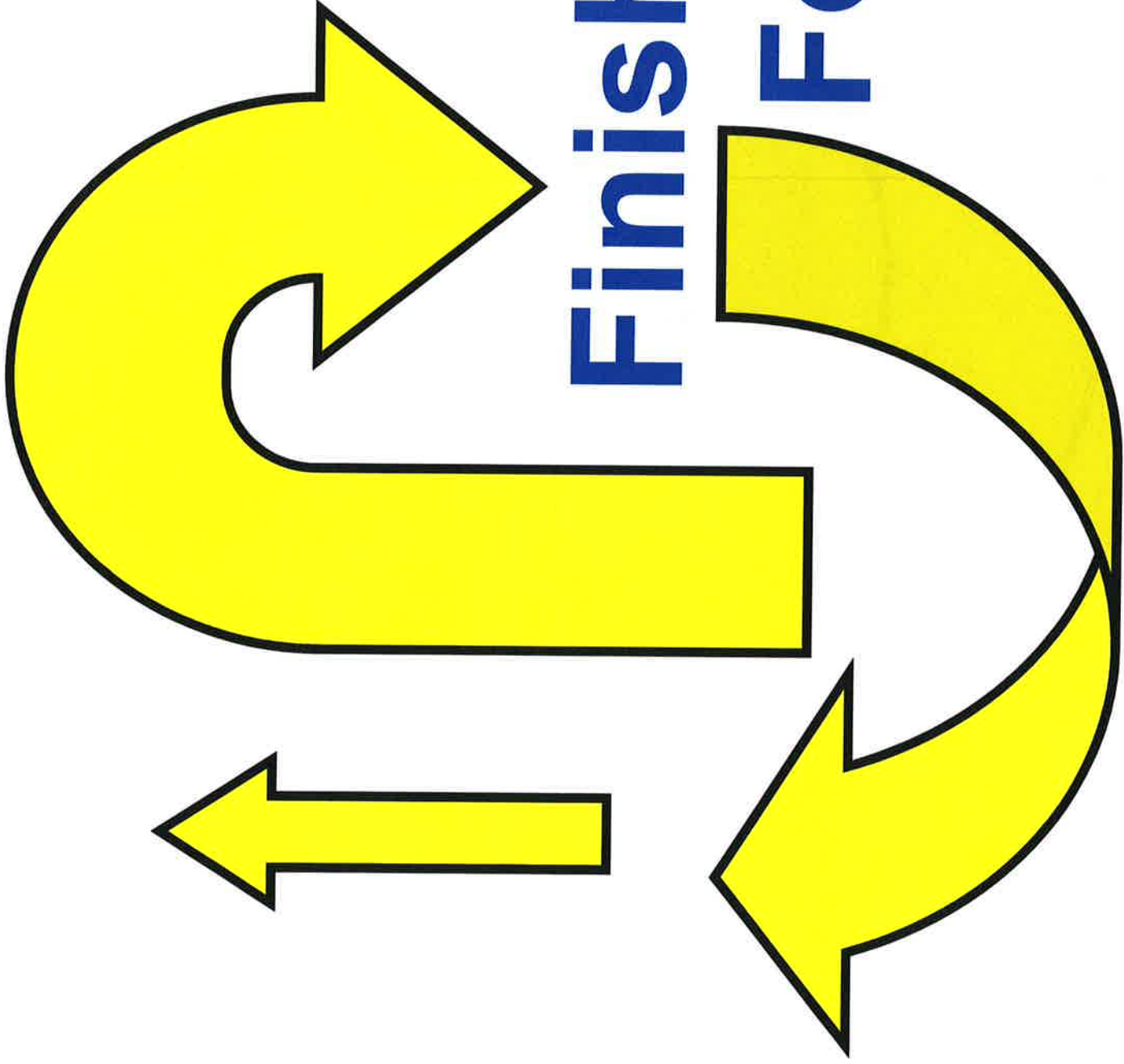
**270°  
Right**

4



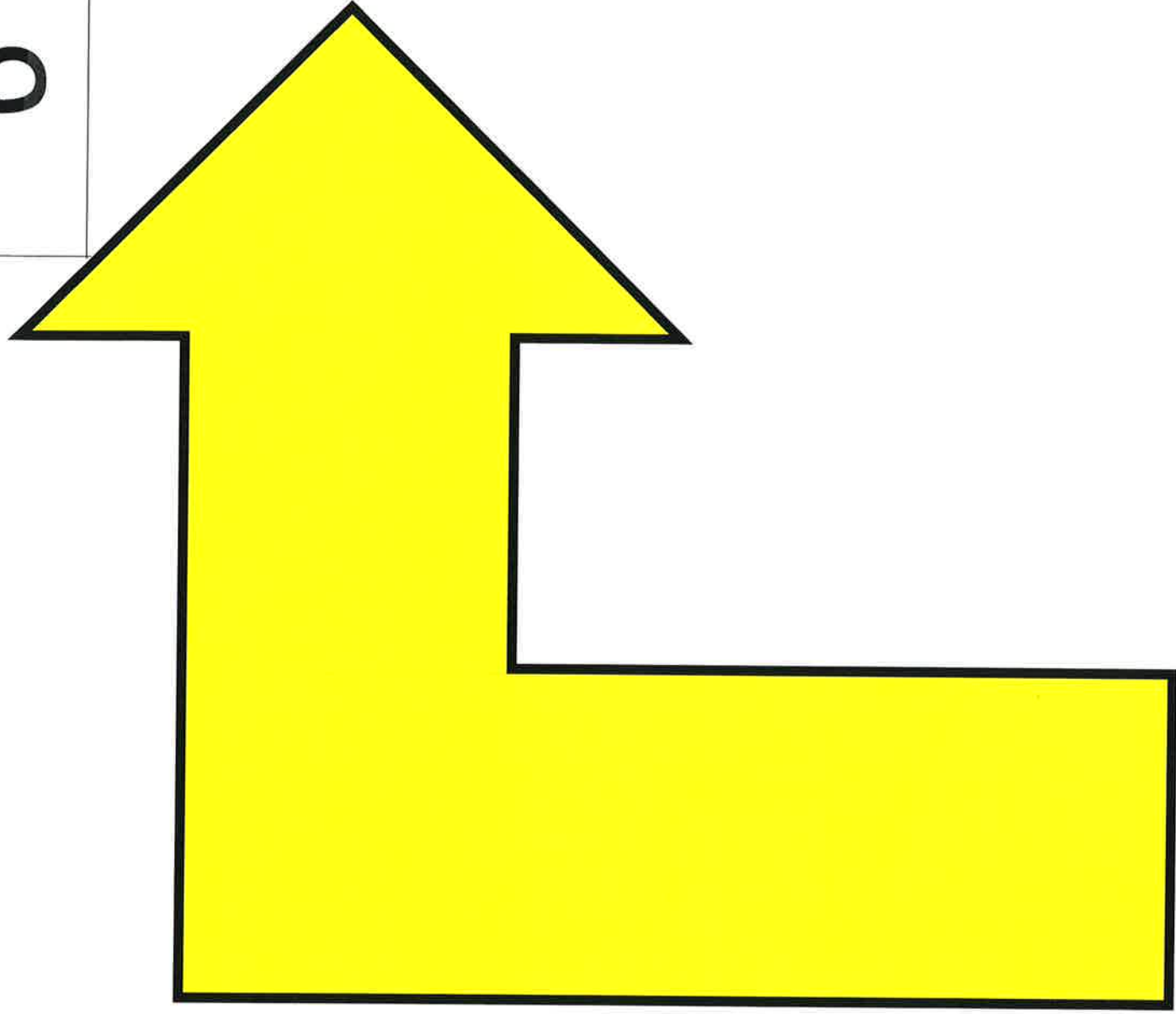
5

**Call**  
**Front**  
**Finish Right**  
**Forward**

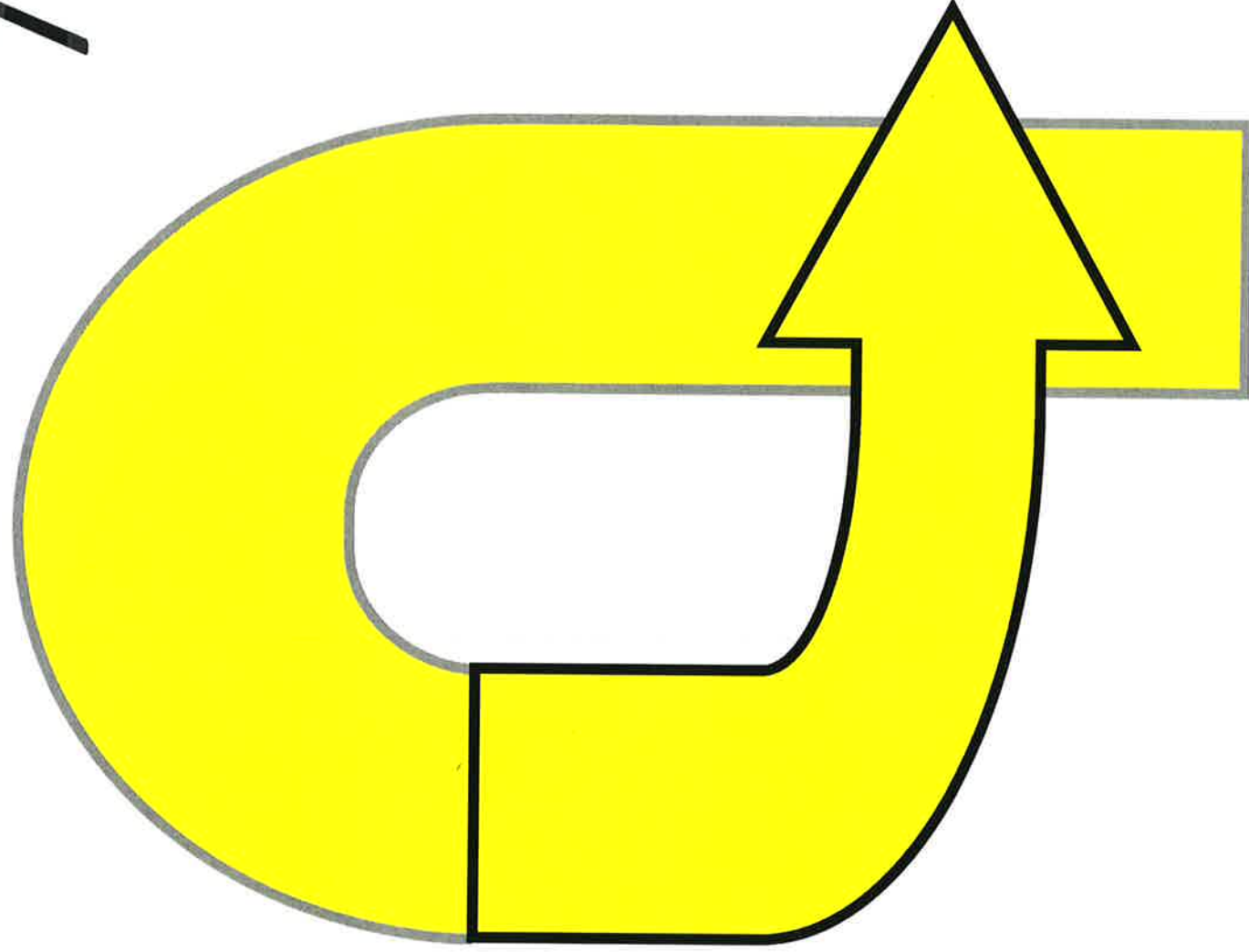




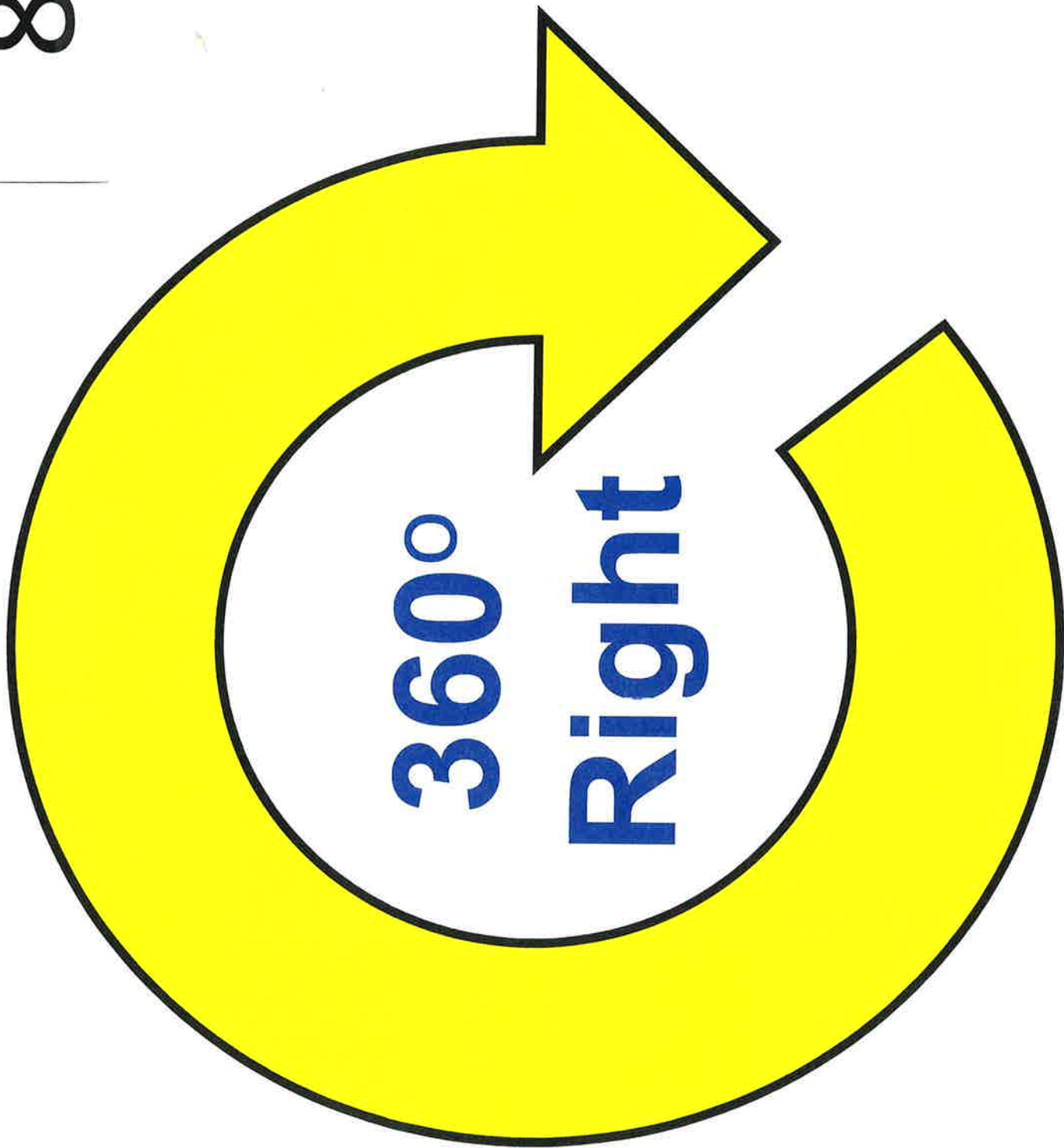
**Right  
Turn**



**270°  
Left**

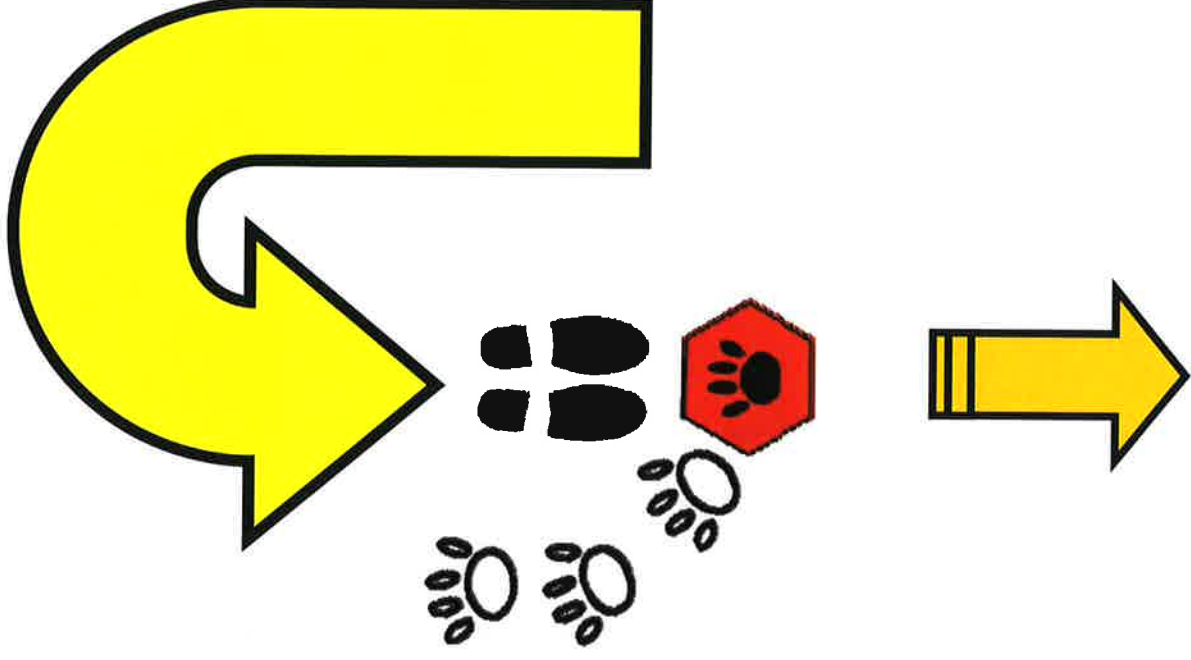


7



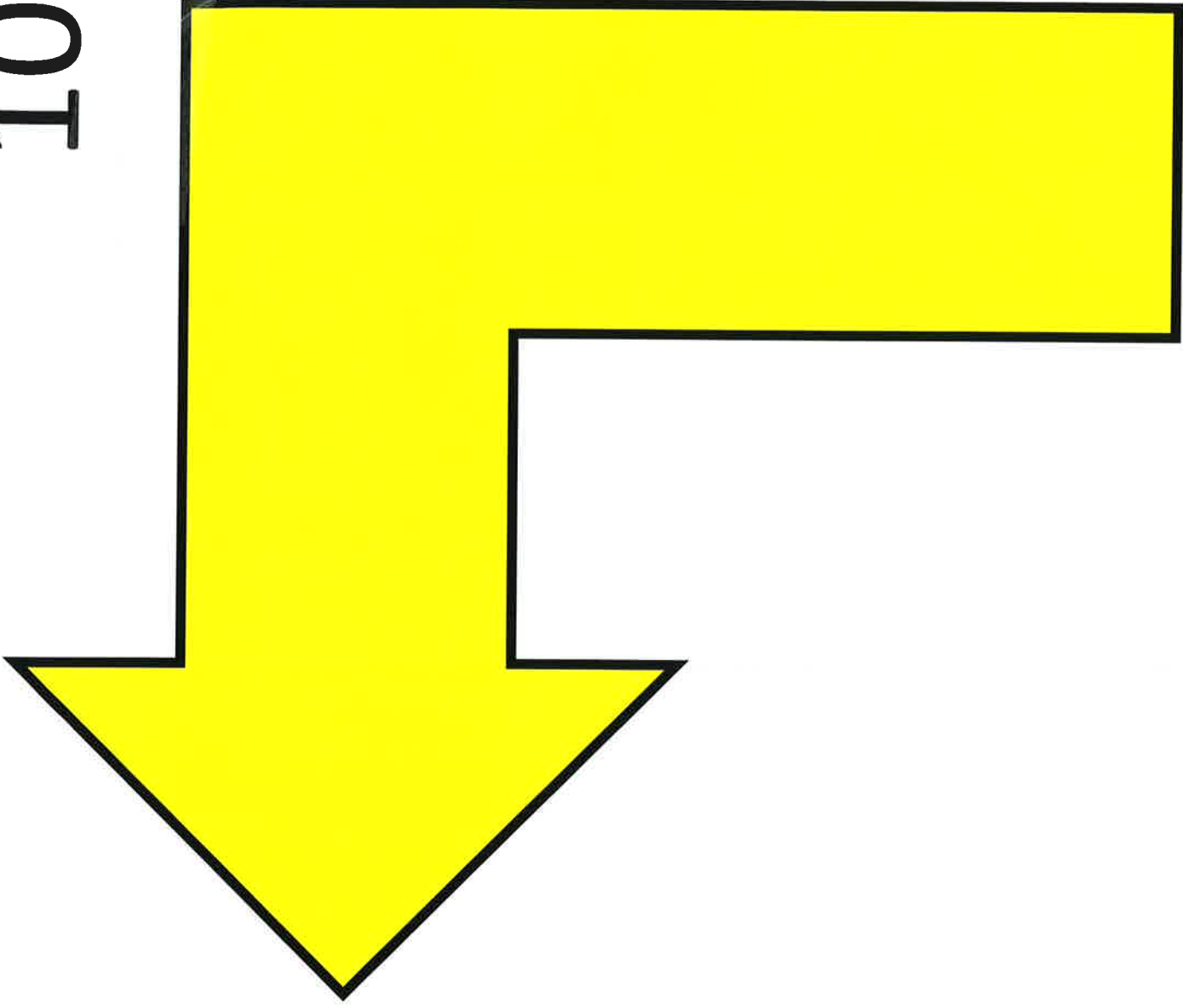


**Step in Front**  
**Finish Right**  
**Forward**

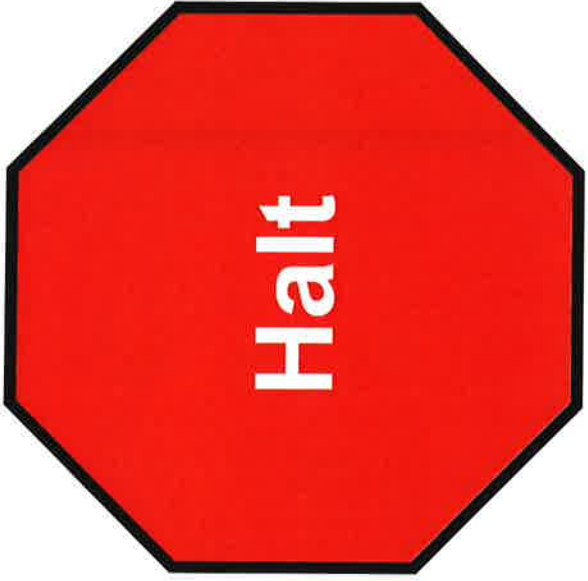
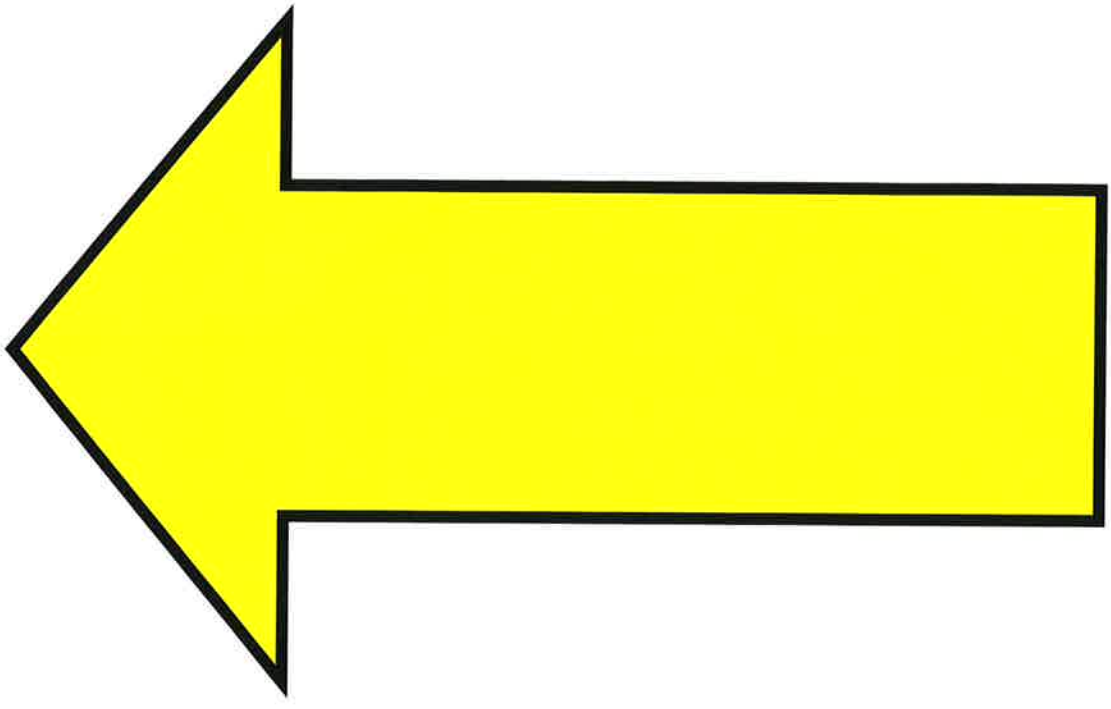


**Left  
Turn**

10



11



**Fast**  
**Forward**  
**From Sit**



**Normal  
Pace**

**N, I, A, X, M- #2**

